Rapid Imaging of Microstructure using Spatially Resolved Acoustic Spectroscopy

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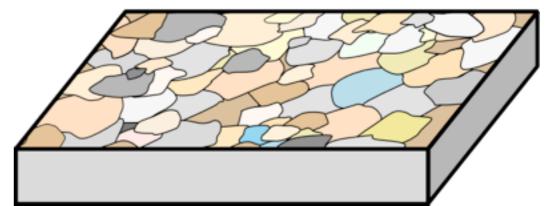
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Aim: to image material microstructure

We would like to image the grain structure of industrially-relevant materials - titanium, aluminium etc.



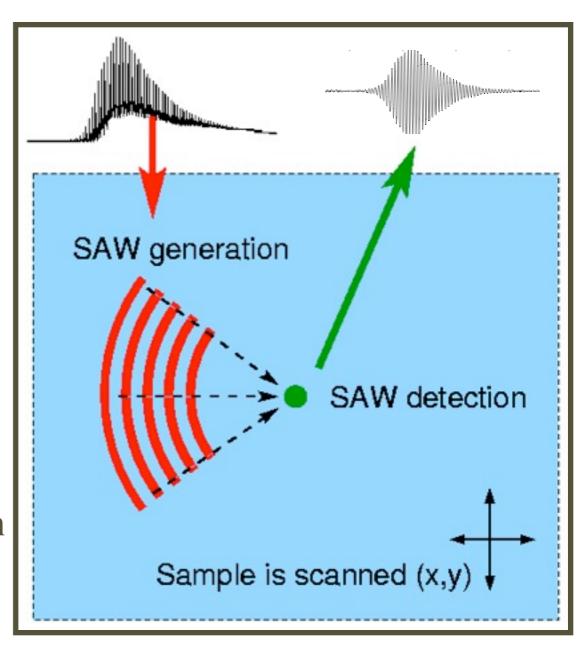
- Several important material properties are structure sensitive:
 - e.g. yield strength, fracture toughness, thermal conductivity
- These are all sensitive to microstructure parameters, such as:
 - Mean grain size
 - Degree of randomness, of both size and orientation
 - Clusters of grains all oriented in the same direction
 - Distribution and volume fraction of second phase particles
- We can use SAW phase velocity which varies with grain orientation as contrast mechanism





Laser ultrasound background... Current system: O-SAM

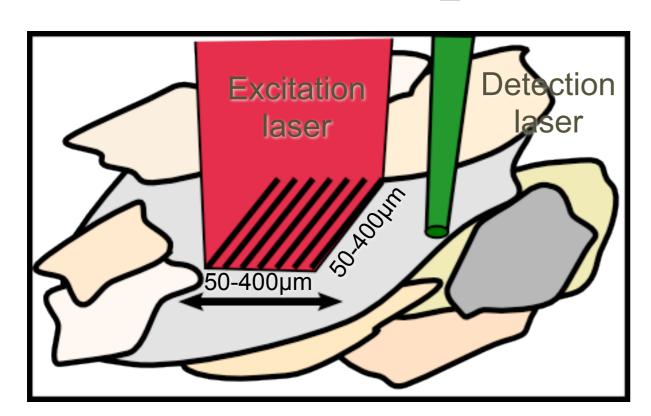
- Pulsed laser source
 - Fundamental frequency 82MHz
 - Repetition rate 1kHz
- Spread out the light
 - Multiple lines
 - lower power density
 - no damage
- Focus the SAWs
 - Higher amplitudes
 - easier and faster detection
- Multiple line source:
 - Generation efficiency depends on how well you match the line spacing to the SAW wavelength

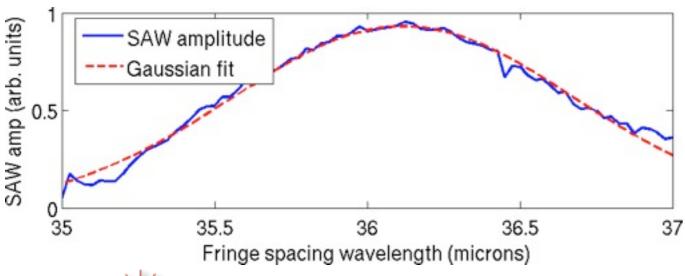






SRAS: spatially resolved acoustic spectroscopy





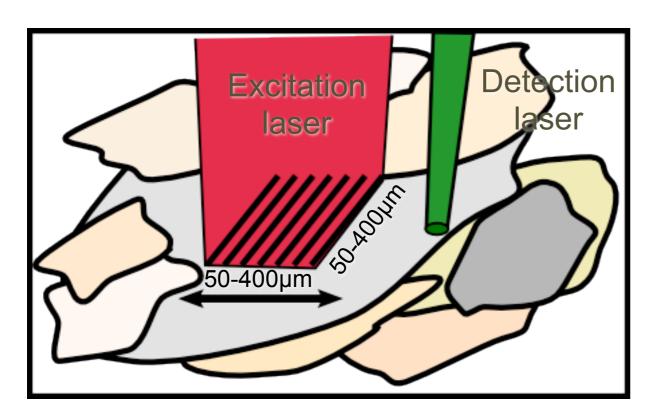
- Fixed excitation frequency (82 or 164 or 328MHz)
- To find phase velocity of material in the area of excitation, we vary the fringe spacing of the excitation source
- When the fringe spacing matches the SAW wavelength, we get the best signal

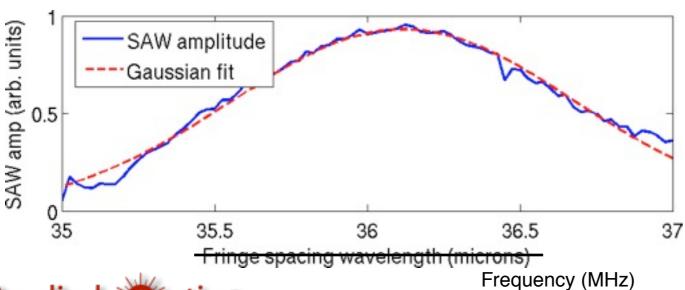
$$v = f\lambda$$





SRAS: spatially resolved acoustic spectroscopy





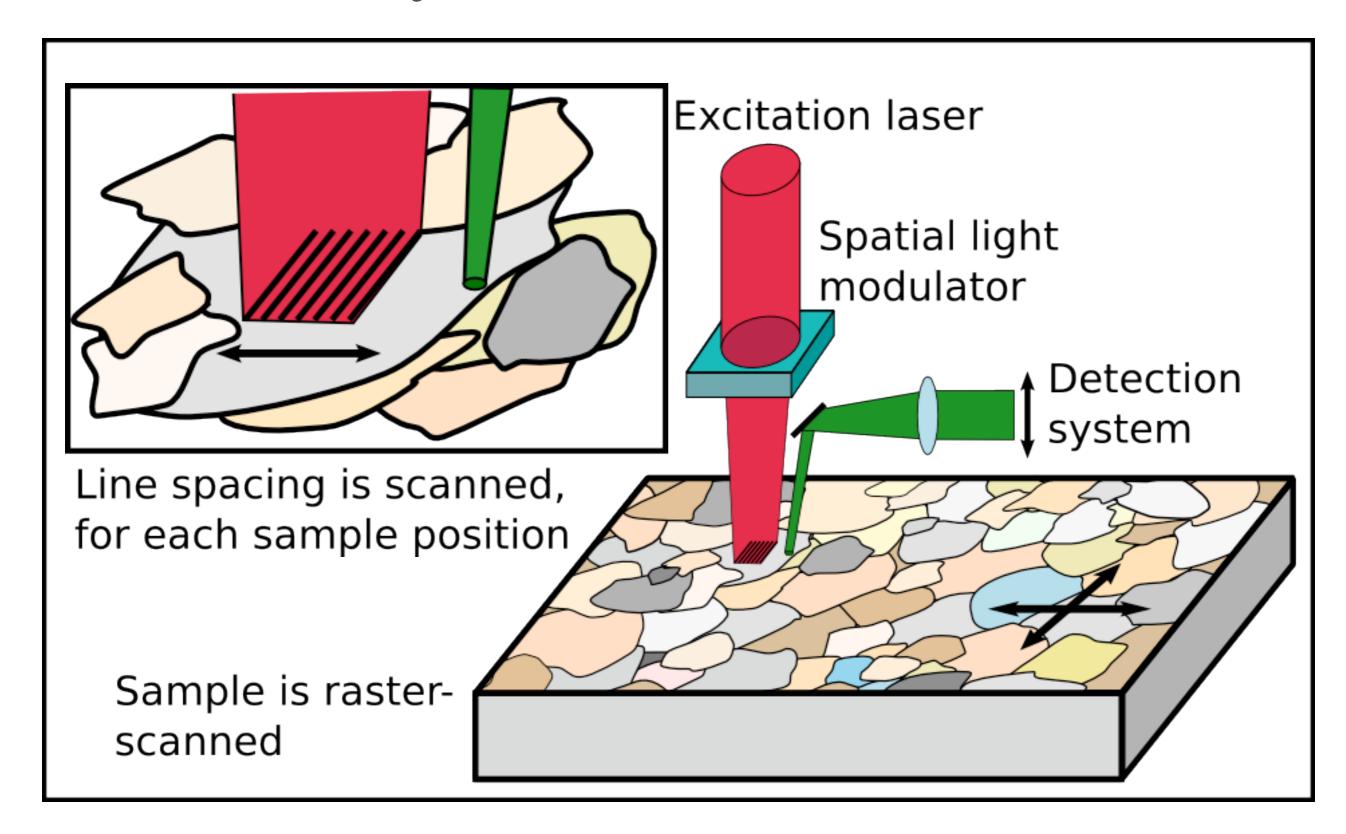
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- Alternatively...
- Broad excitation frequency (over several hundred MHz)
- To find phase velocity of material in the area of excitation, we keep the fringe spacing of the excitation source fixed
- Measure the peak frequency of the detected waves... same formula:

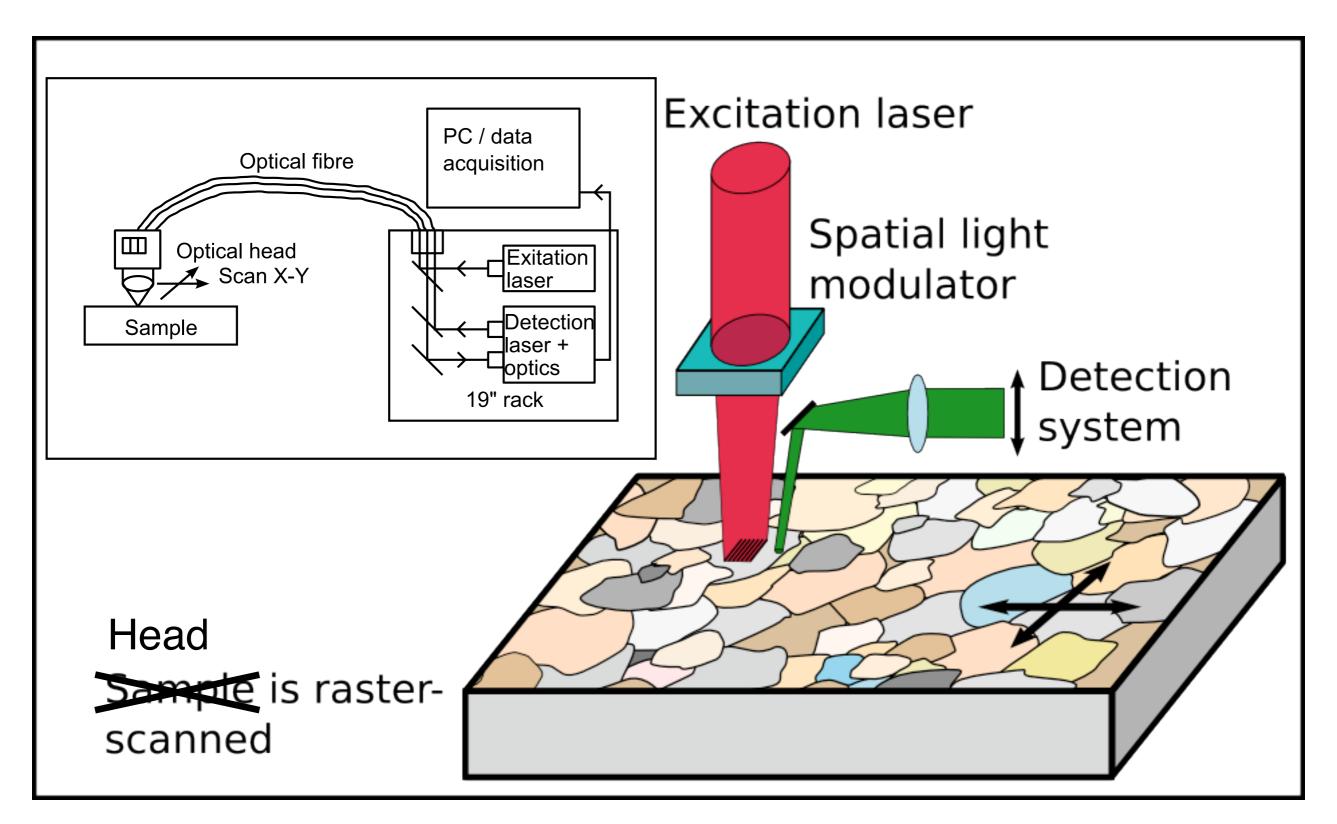
$$v = f\lambda$$



System schematic



System schematic



SRAS capabilities

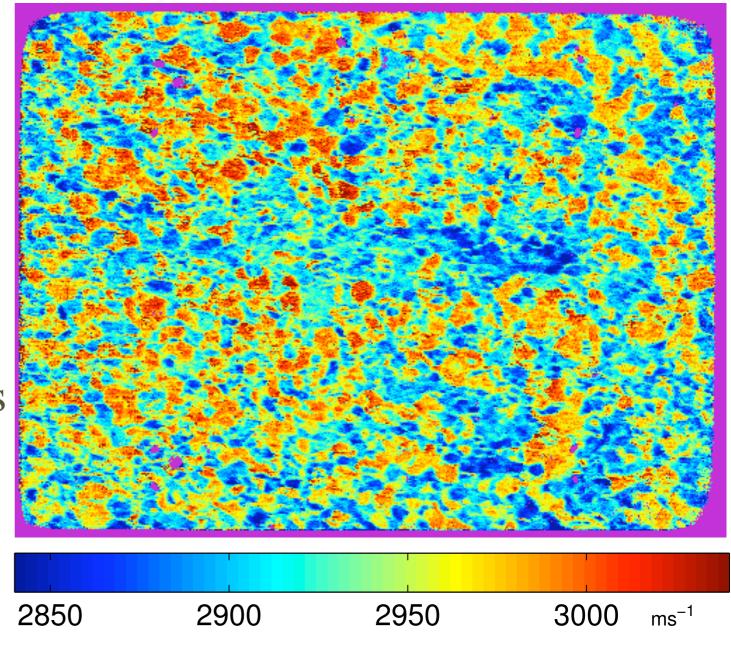
- Lateral (spatial) resolution determined by SLM image size
 - Current spatial resolution is approximately 25μm
- Velocity resolution determined by signal/noise and number of fringes, if curve-fitting is used
 - On a good sample, the best velocity resolution is $\pm 1.5 \text{ms}^{-1}$ (approximately 0.03%)
- Scanning speed:
 - Current practical speed for great results: 10-20 points/sec
 - Up to ~100 points/sec in present configuration
 - Potential to go much higher than this





Grain clusters in titanium alloy

- 76x57mm velocity map of titanium alloy
- Colours represent SAW phase velocity in horizontal direction
- Dark blue region indicates cluster of grains of similar orientation
- Pixel size is 150μm
- Acquisition time was under 3 hours (approx 200,000 pixels)

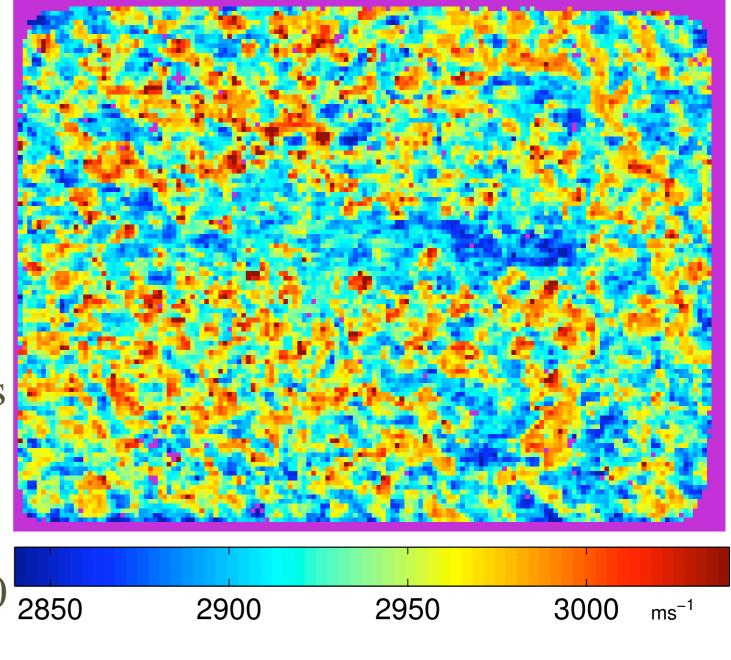






Grain clusters in titanium alloy

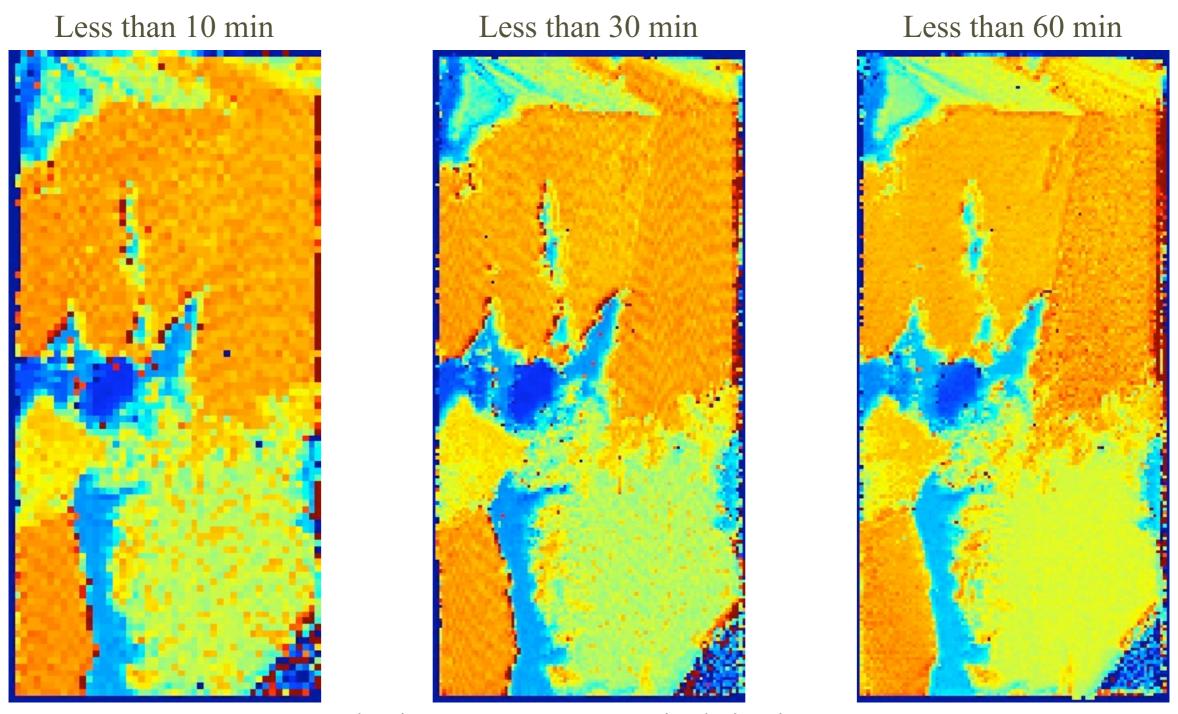
- 76x57mm velocity map of titanium alloy
- Colours represent SAW phase velocity in horizontal direction
- Dark blue region indicates cluster of grains of similar orientation
- Pixel size is 500μm
- Acquisition time was under 18 minutes (17,600 pixels)







Demonstration of speed of system

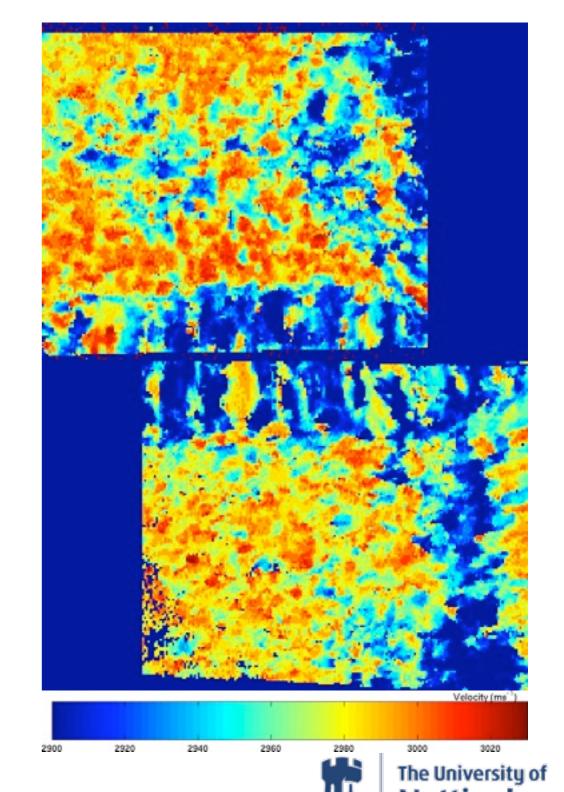






Aluminium

- Large-grained aluminium
- Two samples, each approximately 50x40mm
- Used to be part of the same block when cast
- Grains have preferential orientation where molten aluminium was stirred





Iron and steel

- Iron stock with steel layer, tempered in the traditional way
- Archaeological interest in being able to test the thickness of steel plating nondestructively



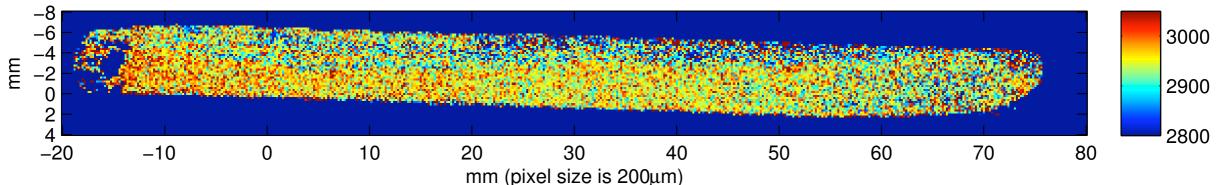






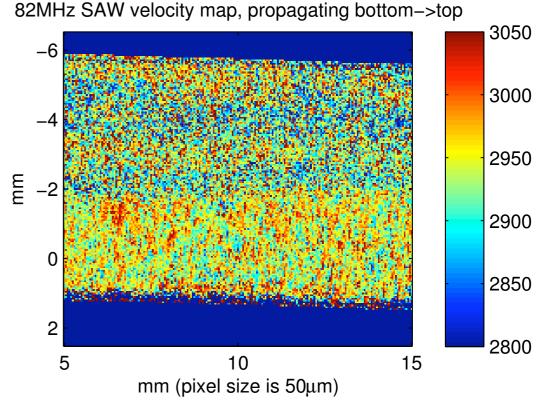
Iron and steel

82MHz SAW velocity map, propagating bottom->top





- SRAS velocity maps of the sample (iron at top, steel below)
- Note small grain size: lateral resolution ~200 microns
- SRAS as validation tool for bulk wave techniques to determine steel thickness

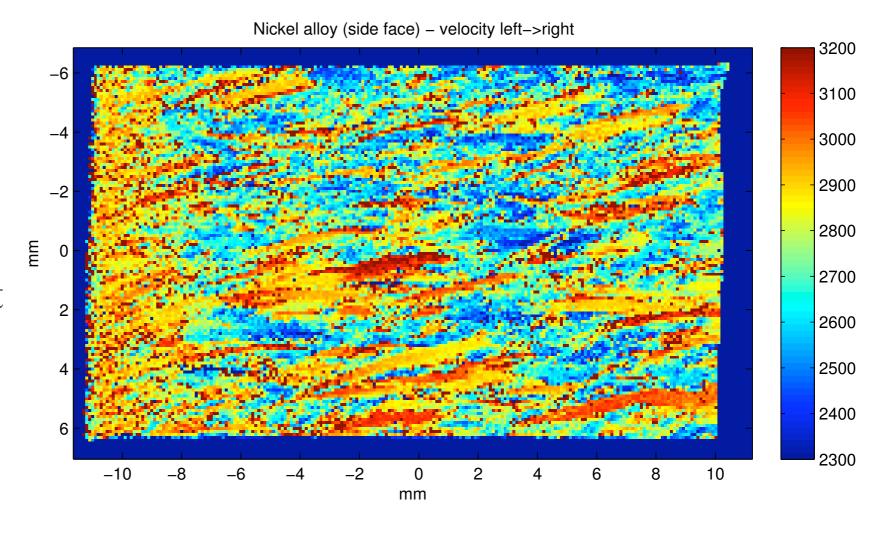






Nickel alloy

- Note velocity scale: very high degree of anisotropy
- SRAS is tolerant to acoustic aberration







Grain orientation from velocity measurement in >1 direction

- Crystals are 3D in structure, e.g. titanium crystals can be:
 - hexagonal close packed (HCP) in the alpha phase
 - body cubic centred (BCC) in the beta phase
- Velocity can vary greatly (e.g. 50%) between parallel and perpendicular directions, relative to basal plane for certain materials
- By scanning at orthogonal angles, can get an idea of the angle of the basal plane

Fast velocities across basal plane



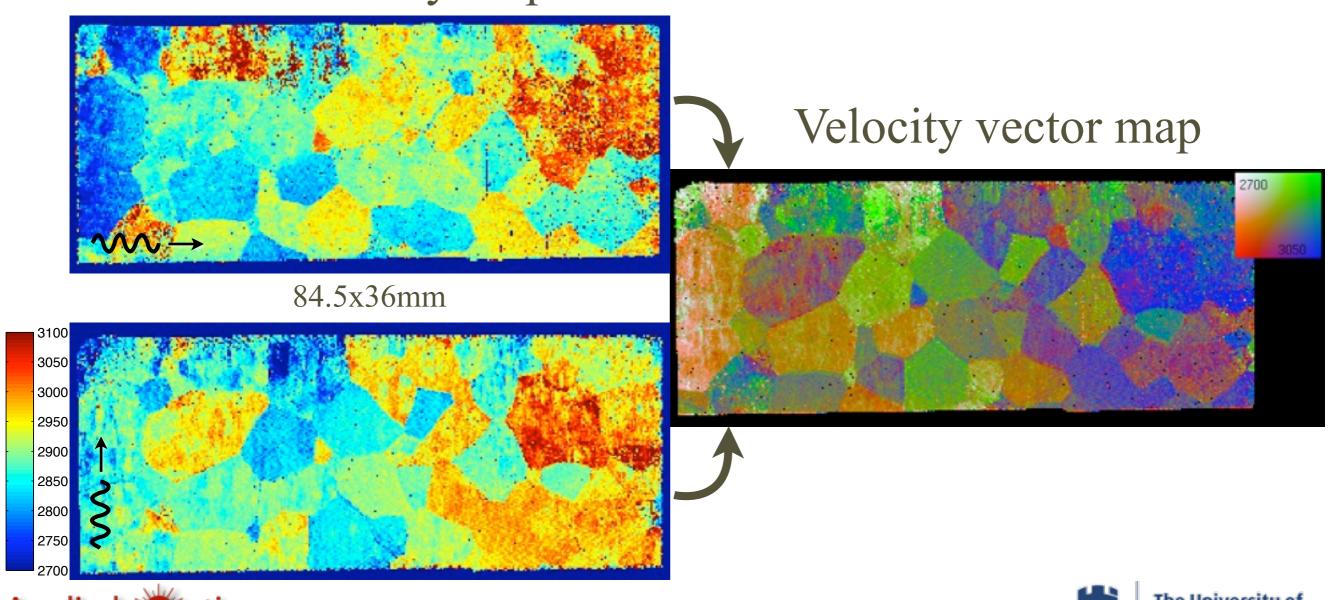
Slow





Ti-6246: velocity vector map

SAW velocity maps

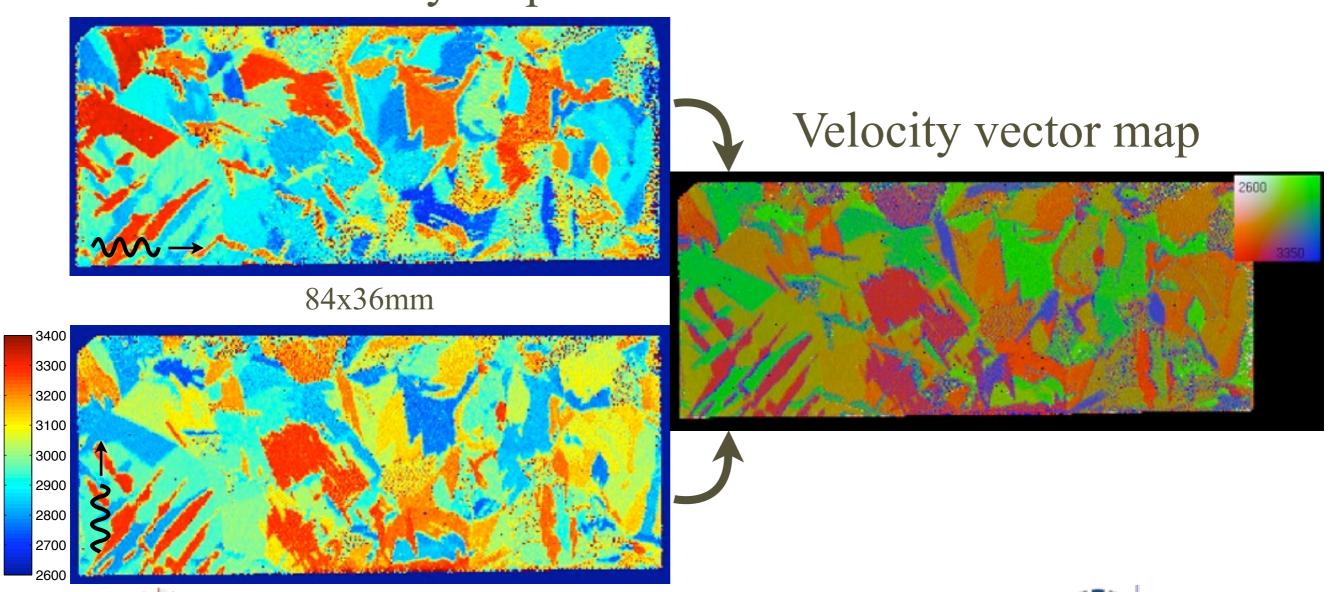






Ti-685: velocity vector map

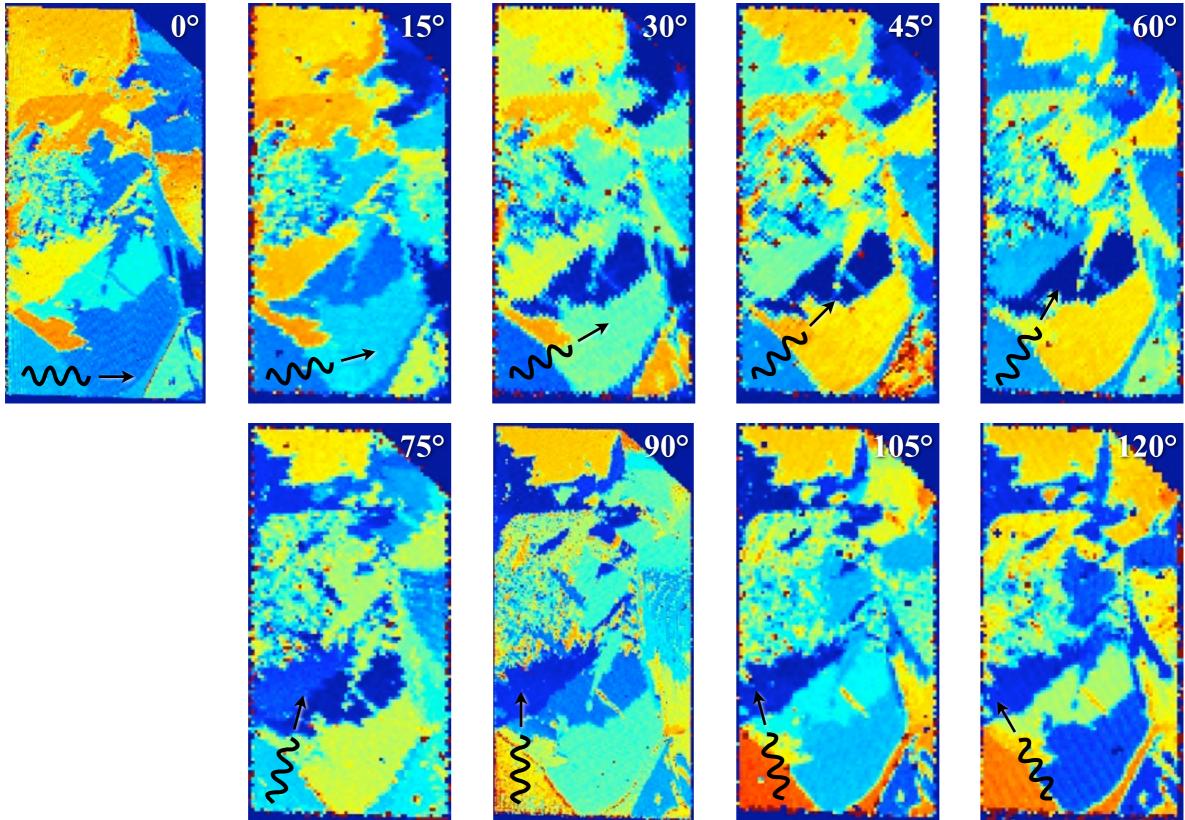
SAW velocity maps



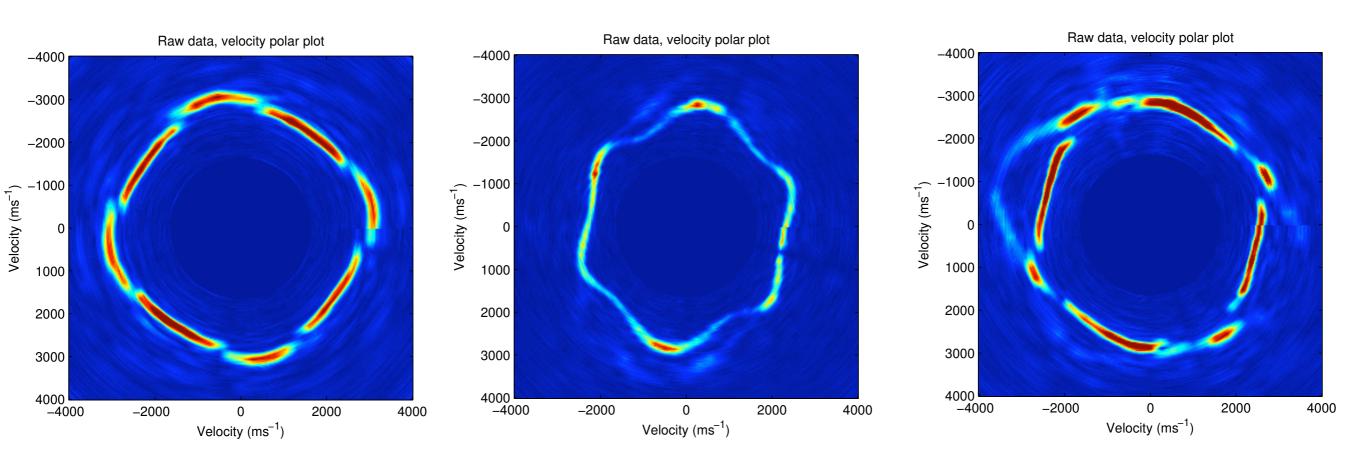




Propagation in multiple directions



Propagation in all directions



Comparison of SRAS with chemical etching and EBSD

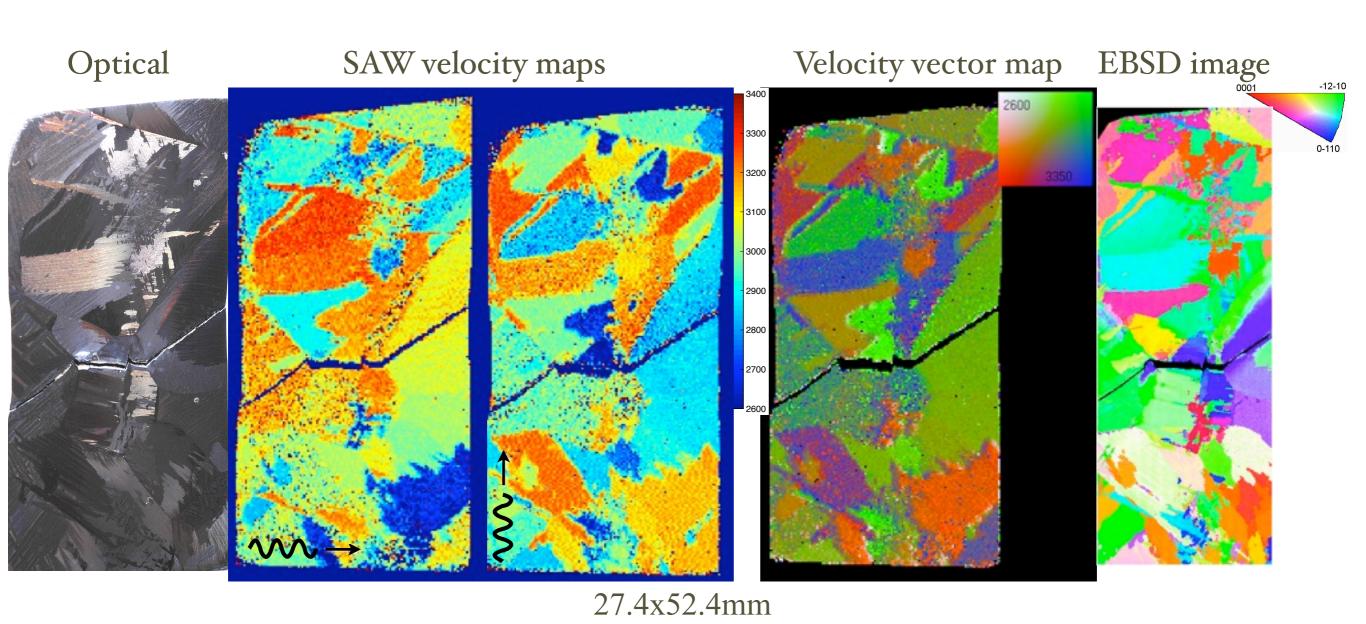
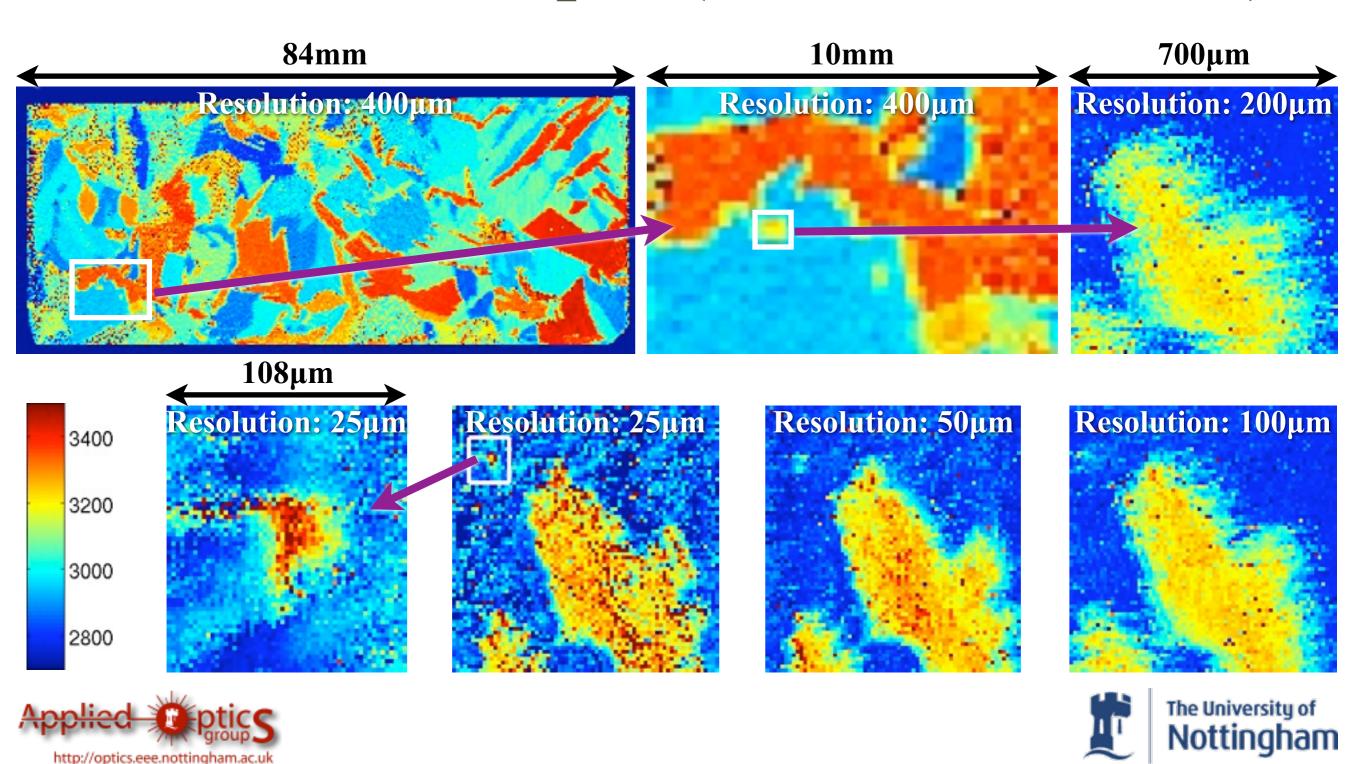
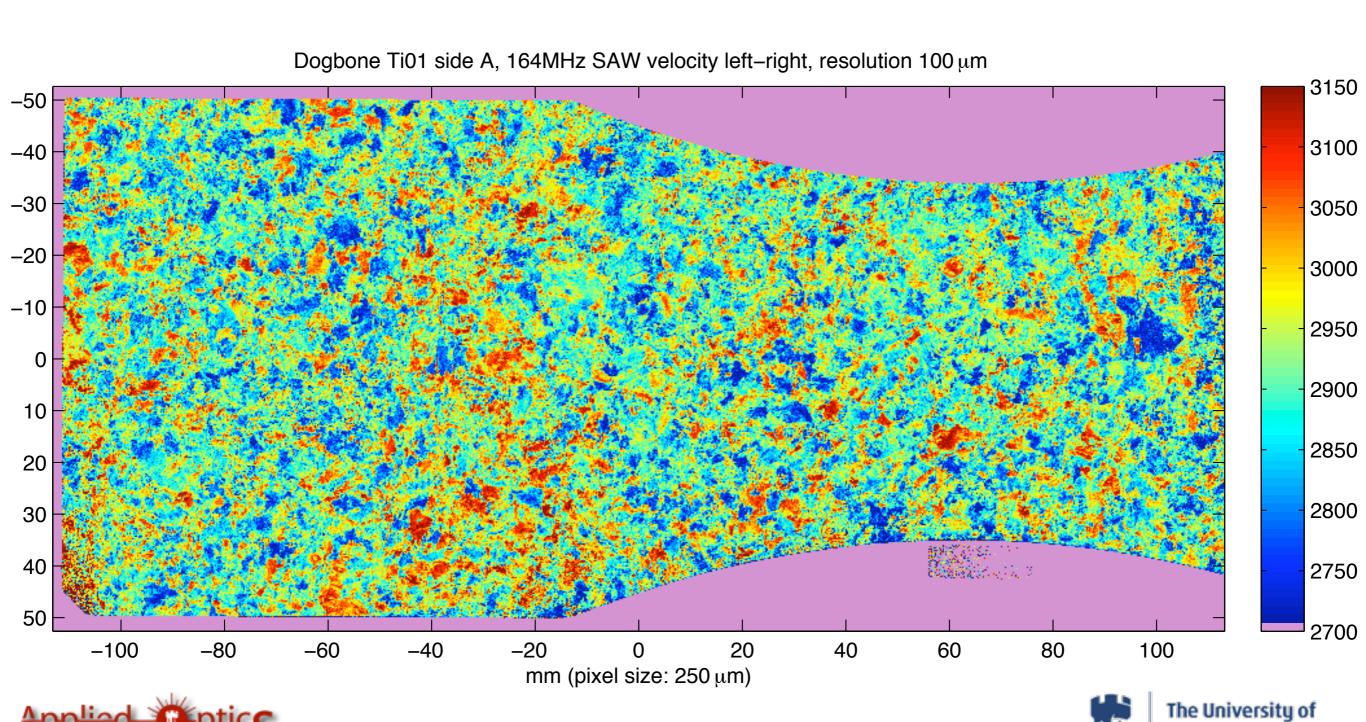


Illustration of the scaleability of the SRAS technique (328MHz SAWs)

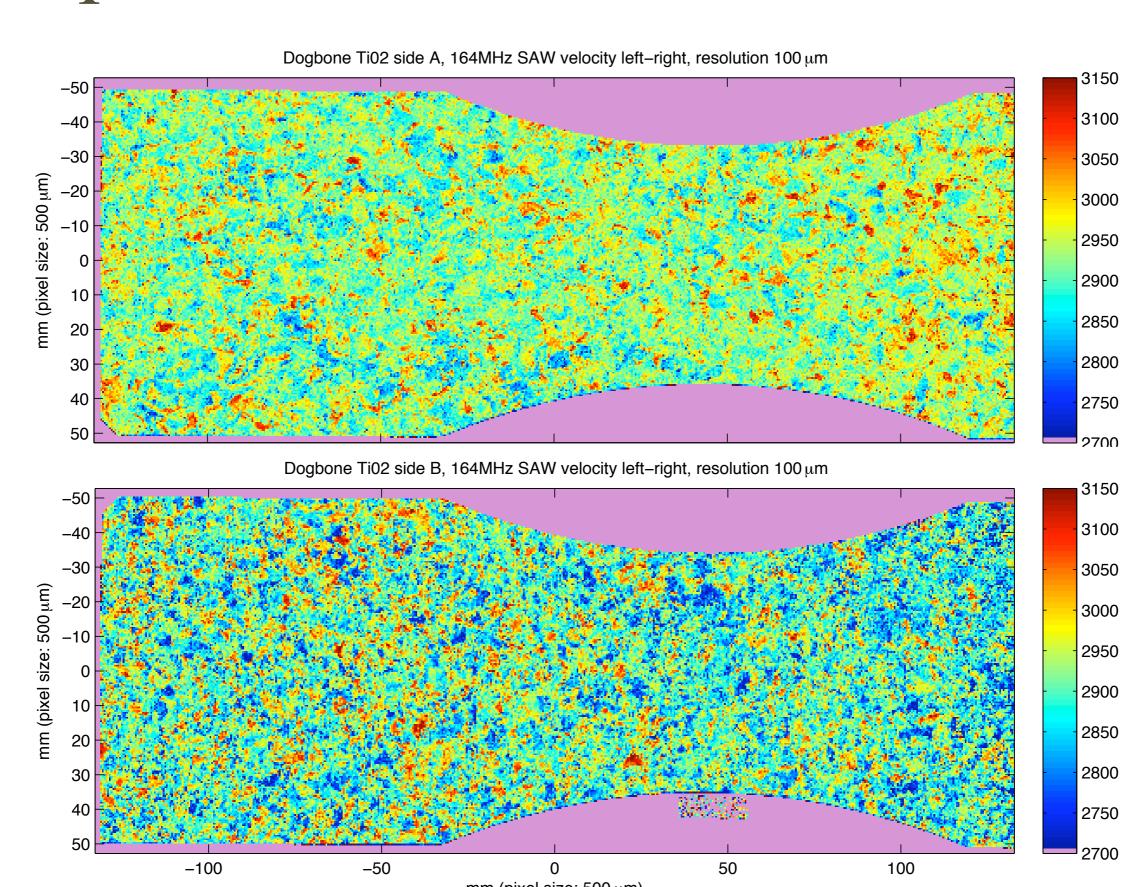


Ability to image large samples, as well as small



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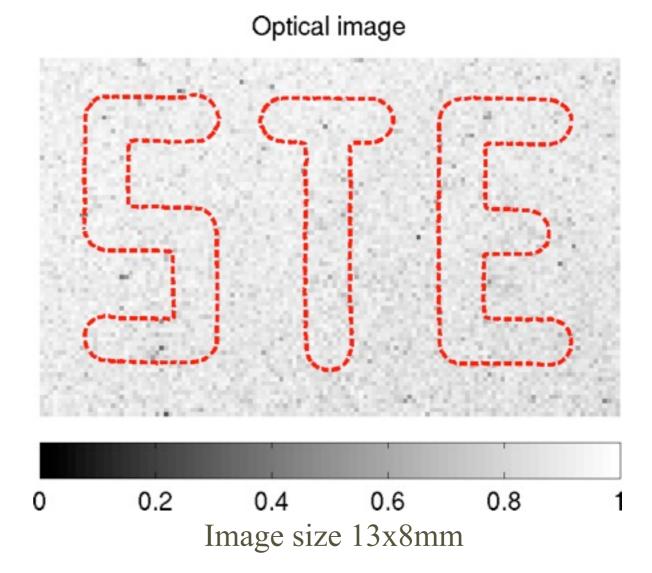
Important microstruture differences



Velocity change as a function of coating thickness

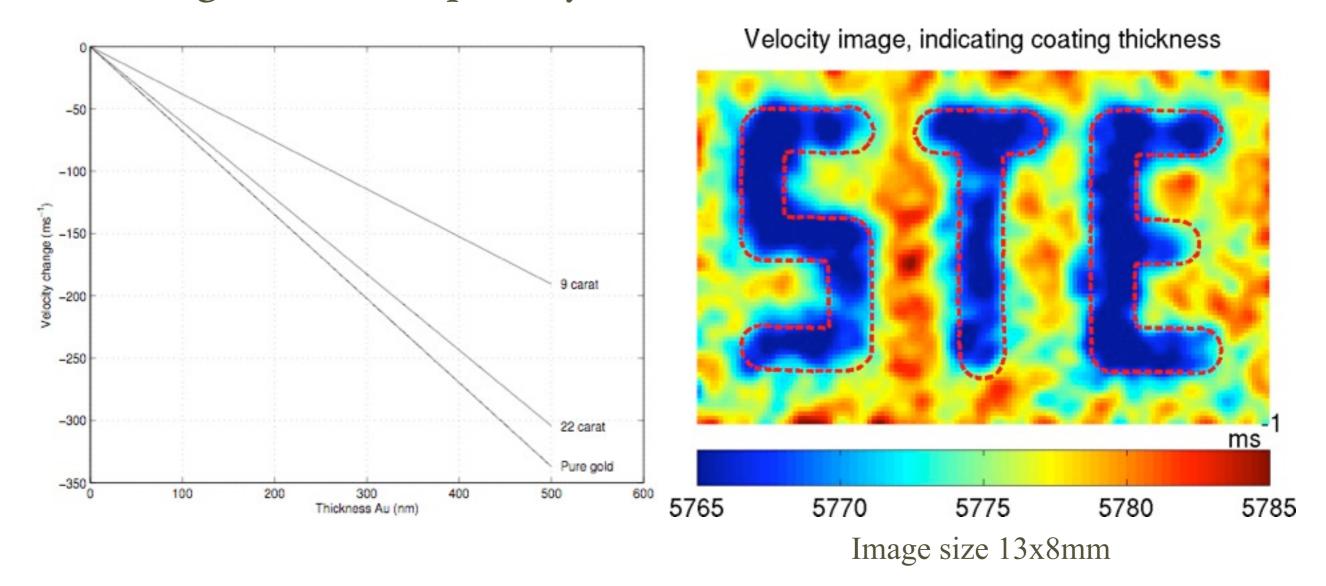
 Large block of silicon nitride is coated with ~30nm of high purity gold, through a mask consisting of three capital letters*

- Mask is removed, then entire area is coated with ~500nm of aluminium
- Gold letters are completely obscured



Velocity change as a function of coating thickness

- Velocity map is acquired, and hidden gold layer is revealed due to change in velocity
- Image has been spatially filtered to reduce noise



SRAS: Conclusions

- Spatially Resolved Acoustic Spectroscopy is a **robust** and **rapid** technique for **quantitatively** measuring the SAW phase velocity
- It is non-contact and is completely non-destructive
 - Excitation powers <15mW have been used
- Lateral resolution is currently approximately 25μm
- Sample size limited only by scanning stages
- Trade-offs between lateral resolution and velocity resolution: the higher the frequency the better
- More work needs to be done to relate SAW velocity in multiple directions with crystallographic orientation





Thanks for your attention



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